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### Main

|                                    |   |
|------------------------------------|---|
| Range of product                   | Altivar Process ATV600  |
| Product or component type          | Variable speed drive  |
| Product specific application       | Process and utilities   |
| Device short name                  | ATV630  |
| Variant                            | Standard version  |
| Product destination                | Asynchronous motors<br>Synchronous motors   |
| EMC filter                         | Without EMC filter  |
| IP degree of protection            | IP21 conforming to IEC 61800-5-1<br>IP21 conforming to IEC 60529  |
| Degree of protection               | UL type 1 conforming to UL 508C   |
| Type of cooling                    | Forced convection   |
| Supply frequency                   | 50...60 Hz - 5...5 %  |
| Network number of phases           | 3 phases  |
| [Us] rated supply voltage          | 200...240 V - 15...10 %   |
| Motor power kW                     | 37 KW (normal duty)<br>30 kW (heavy duty)   |
| Motor power hp                     | 50 Hp normal duty<br>40 hp heavy duty   |
| Line current                       | 128 A at 200 V (normal duty)<br>107.8 A at 240 V (normal duty)<br>104.7 A at 200 V (heavy duty)<br>88.6 A at 240 V (heavy duty) |
| Prospective line Isc               | 50 kA   |
| Apparent power                     | 44.8 KVA at 240 V (normal duty)<br>36.8 kVA at 240 V (heavy duty)   |
| Continuous output current          | 149 A at 2.5 kHz for normal duty<br>123 A at 2.5 kHz for heavy duty   |
| Maximum transient current          | 163.9 A during 60 s (normal duty)<br>184.5 A during 60 s (heavy duty)   |
| Asynchronous motor control profile | Variable torque standard<br>Optimized torque mode<br>Constant torque standard   |
| Synchronous motor control profile  | Permanent magnet motor<br>Synchronous reluctance motor  |
| Output frequency                   | 0.0001...0.5 kHz  |
| Speed drive output frequency       | 0.1...599 Hz  |
| Nominal switching frequency        | 2.5 kHz   |
| Switching frequency                | 2.5...8 kHz with derating factor<br>2...8 kHz adjustable  |
| Safety function                    | STO (safe torque off) SIL 3   |
| Discrete input logic               | 16 preset speeds  |

|                             |  |
|-----------------------------|--|
| Communication port protocol | Modbus serial<br>Ethernet<br>Modbus TCP  |
| Option card                 | Slot A: communication module, Profibus DP V1<br>Slot A: communication module, Profinet<br>Slot A: communication module, DeviceNet<br>Slot A: communication module, Modbus TCP/<br>EtherNet/IP<br>Slot A: communication module, CANopen daisy<br>chain RJ45<br>Slot A: communication module, CANopen SUB-D 9<br>Slot A: communication module, CANopen screw<br>terminals<br>Slot A/slot B: digital and analog I/O extension<br>module<br>Slot A/slot B: output relay extension module<br>Slot A: communication module, Ethernet IP/Modbus<br>TCP/M-D-Link<br>Communication module, BACnet MS/TP<br>Communication module, Ethernet Powerlink |

## Complementary

|                                     |  |
|-------------------------------------|--|
| Output voltage                      | <= power supply voltage  |
| Permissible temporary current boost | 1.1 x In during 60 s (normal duty)<br>1.5 x In during 60 s (heavy duty)  |
| Motor slip compensation             | Can be suppressed<br>Not available in permanent magnet motor law<br>Automatic whatever the load<br>Adjustable  |
| Acceleration and deceleration ramps | Linear adjustable separately from 0.01...9999 s  |
| Braking to standstill               | By DC injection  |
| Protection type                     | Thermal protection: motor<br>Safe torque off: motor<br>Motor phase break: motor<br>Thermal protection: drive<br>Safe torque off: drive<br>Overheating: drive<br>Overcurrent between output phases and earth: drive<br>Overload of output voltage: drive<br>Short-circuit protection: drive<br>Motor phase break: drive<br>Overvoltages on the DC bus: drive<br>Line supply overvoltage: drive<br>Line supply undervoltage: drive<br>Line supply phase loss: drive<br>Overspeed: drive<br>Break on the control circuit: drive |
| Frequency resolution                | Display unit: 0.1 Hz<br>Analog input: 0.012/50 Hz  |
| Electrical connection               | Control: removable screw terminals 0.5...1.5 mm <sup>2</sup> /AWG 20...AWG 16<br>Line side: screw terminal 70...120 mm <sup>2</sup> /AWG 2/0...250 kcmil<br>Motor: screw terminal 95...120 mm <sup>2</sup> /AWG 3...250 kcmil  |
| Connector type                      | RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP<br>RJ45 (on the remote graphic terminal) for Modbus serial   |
| Physical interface                  | 2-wire RS 485 for Modbus serial  |
| Transmission frame                  | RTU for Modbus serial  |
| Transmission rate                   | 10/100 Mbit/s for Ethernet IP/Modbus TCP<br>4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial  |
| Exchange mode                       | Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP  |
| Data format                         | 8 bits, configurable odd, even or no parity for Modbus serial  |
| Type of polarization                | No impedance for Modbus serial   |
| Number of addresses                 | 1...247 for Modbus serial  |
| Method of access                    | Slave Modbus TCP   |
| Supply                              | External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type:<br>overload and short-circuit protection<br>Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %,<br><10 mA, protection type: overload and short-circuit protection<br>Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA,<br>protection type: overload and short-circuit protection  |

|                           |  |
|---------------------------|--|
| Local signalling          | 3 LEDs for local diagnostic<br>3 LEDs (dual colour) for embedded communication status<br>4 LEDs (dual colour) for communication module status<br>1 LED (red) for presence of voltage   |
| Width                     | 290 mm   |
| Height                    | 922 mm   |
| Depth                     | 323 mm   |
| Net weight                | 56.6 kg  |
| Analogue input number     | 3  |
| Analogue input type       | AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits<br>AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits   |
| Discrete input number     | 8  |
| Discrete input type       | DI1...DI6 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm<br>DI5, DI6 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V)<br>STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm  |
| Input compatibility       | DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2<br>DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68<br>STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2   |
| Discrete input logic      | Positive logic (source) (DI1...DI6), < 5 V (state 0), > 11 V (state 1)<br>Negative logic (sink) (DI1...DI6), > 16 V (state 0), < 10 V (state 1)<br>Positive logic (source) (DI5, DI6), < 0.6 V (state 0), > 2.5 V (state 1)<br>Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)                                   |
| Analogue output number    | 2  |
| Analogue output type      | Software-configurable voltage AO1, AO2: 0...10 V DC impedance 470 Ohm, resolution 10 bits<br>Software-configurable current AO1, AO2: 0...20 mA, resolution 10 bits   |
| Sampling duration         | 2 Ms +/- 0.5 ms (DI1...DI4) - discrete input<br>5 Ms +/- 1 ms (DI5, DI6) - discrete input<br>5 Ms +/- 0.1 ms (AI1, AI2, AI3) - analog input<br>10 ms +/- 1 ms (AO1) - analog output  |
| Accuracy                  | +/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input<br>+/- 1 % AO1, AO2 for a temperature variation 60 °C analog output   |
| Linearity error           | AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input<br>AO1, AO2: +/- 0.2 % for analog output   |
| Relay output number       | 3  |
| Relay output type         | Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles<br>Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles<br>Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles   |
| Refresh time              | Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)   |
| Minimum switching current | Relay output R1, R2, R3: 5 mA at 24 V DC   |
| Maximum switching current | Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC<br>Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC<br>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC<br>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC |
| Isolation                 | Between power and control terminals  |

|  |  |
|--|--|
| Variable speed drive application selection | Compressor centrifugal Building - HVAC<br>Other application Food and beverage processing<br>Fan Mining mineral and metal<br>Pump Mining mineral and metal<br>Fan Oil and gas<br>Other application Water and waste water<br>Screw compressor Building - HVAC<br>Pump Food and beverage processing<br>Fan Food and beverage processing<br>Atomization Food and beverage processing<br>Electro submersible pump (ESP) Oil and gas<br>Water injection pump Oil and gas<br>Jet fuel pump Oil and gas<br>Compressor for refinery Oil and gas<br>Centrifuge pump Water and waste water<br>Positive displacement pump Water and waste water<br>Electro submersible pump (ESP) Water and waste water<br>Screw pump Water and waste water<br>Lobe compressor Water and waste water<br>Screw compressor Water and waste water<br>Compressor centrifugal Water and waste water<br>Fan Water and waste water<br>Conveyor Water and waste water<br>Mixer Water and waste water |
| Motor power range AC-3                     | 30...50 kW at 200...240 V 3 phases   |
| Mounting mode                              | Wall mount   |

## Environment

|                                       |  |
|---------------------------------------|--|
| Insulation resistance                 | > 1 MOhm 500 V DC for 1 minute to earth  |
| Noise level                           | 62.4 dB conforming to 86/188/EEC   |
| Power dissipation in W                | Natural convection: 156 W at 200 V, switching frequency 2.5 kHz<br>Forced convection: 1141 W at 200 V, switching frequency 2.5 kHz   |
| Volume of cooling air                 | 295 m3/h   |
| Operating position                    | Vertical +/- 10 degree   |
| Maximum THDI                          | <48 % from 80...100 % of load conforming to IEC 61000-3-12   |
| Electromagnetic compatibility         | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 |
| Pollution degree                      | 2 conforming to EN/IEC 61800-5-1   |
| Vibration resistance                  | 1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6<br>1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6  |
| Shock resistance                      | 15 gn for 11 ms conforming to IEC 60068-2-27   |
| Relative humidity                     | 5...95 % without condensation conforming to IEC 60068-2-3  |
| Ambient air temperature for operation | -15...50 °C (without derating)<br>50...60 °C (with derating factor)  |
| Ambient air temperature for storage   | -40...70 °C  |
| Operating altitude                    | <= 1000 m without derating<br>1000...4800 m with current derating 1 % per 100 m  |
| Environmental characteristic          | Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3<br>Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3   |
| Standards                             | UL 508C<br>EN/IEC 61800-3<br>Environment 1 category C2 EN/IEC 61800-3<br>Environment 2 category C3 EN/IEC 61800-3<br>EN/IEC 61800-5-1<br>IEC 61000-3-12<br>IEC 60721-3<br>IEC 61508<br>IEC 13849-1   |
| Product certifications                | REACH<br>ATEX INERIS<br>DNV-GL<br>UL<br>TÜV<br>ATEX zone 2/22<br>CSA   |
| Marking                               | CE   |

## Packing Units

|                              |        |
|------------------------------|--------|
| Unit Type of Package 1       | PCE    |
| Number of Units in Package 1 | 1      |
| Package 1 Weight             | 55 kg  |
| Package 1 Height             | 42 cm  |
| Package 1 width              | 57 cm  |
| Package 1 Length             | 105 cm |

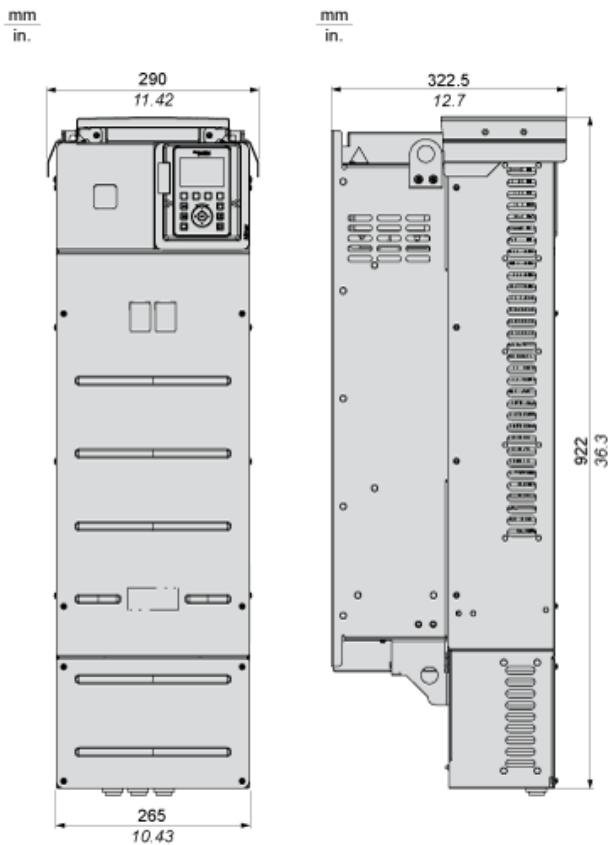
## Offer Sustainability

|                            |  |
|----------------------------|--|
| Sustainable offer status   | Green Premium product  |
| REACH Regulation           |  REACH Declaration  |
| EU RoHS Directive          | Pro-active compliance (Product out of EU RoHS legal scope)  EU RoHS Declaration |
| Mercury free               | Yes  |
| RoHS exemption information |  Yes  |
| China RoHS Regulation      |  China RoHS Declaration   |
| Environmental Disclosure   |  Product Environmental Profile  |
| Circularity Profile        |  End Of Life Information  |
| WEEE                       | The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins  |
| Upgradeability             |  Upgraded Components Available  |

## Dimensions

### Drives with IP21 Top Cover

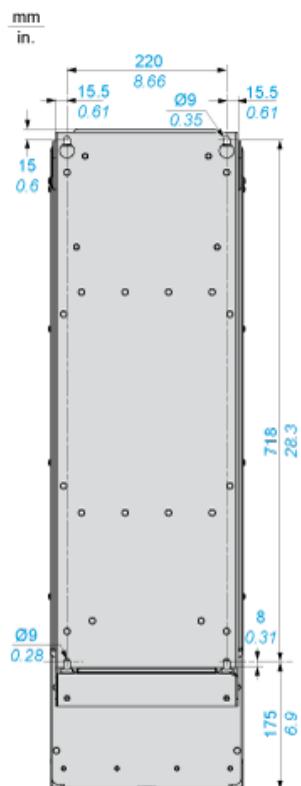
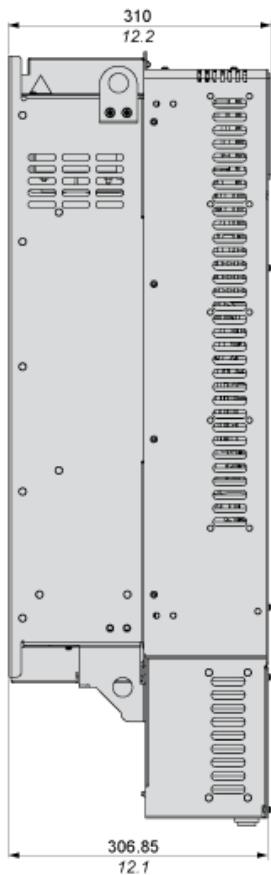
#### Front and Left Views



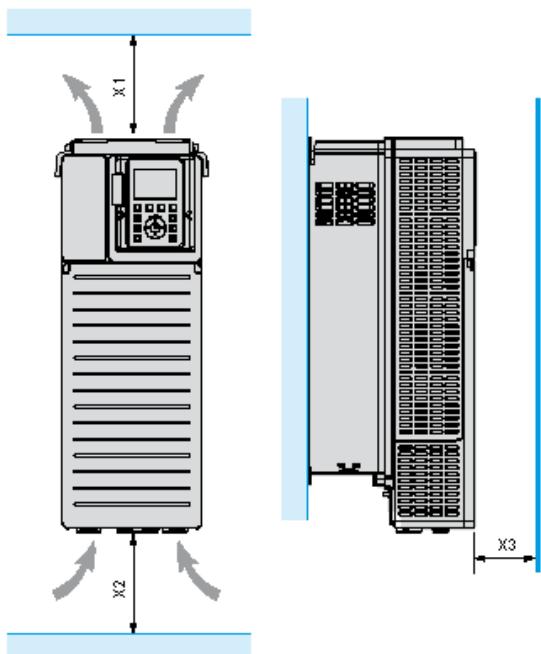
### Drives Without IP21 Top Cover

#### Left and Rear Views

mm  
in.



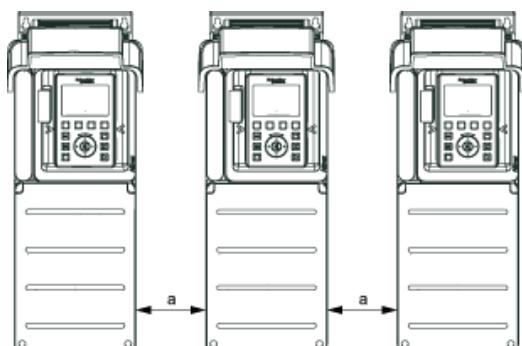
### Clearances



| X1                               | X2                               | X3                              |
|----------------------------------|----------------------------------|---------------------------------|
| $\geq 100 \text{ mm (3.94 in.)}$ | $\geq 100 \text{ mm (3.94 in.)}$ | $\geq 10 \text{ mm (0.39 in.)}$ |

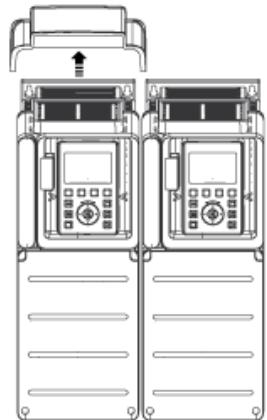
### Mounting Types

#### Mounting Type A: Individual IP21

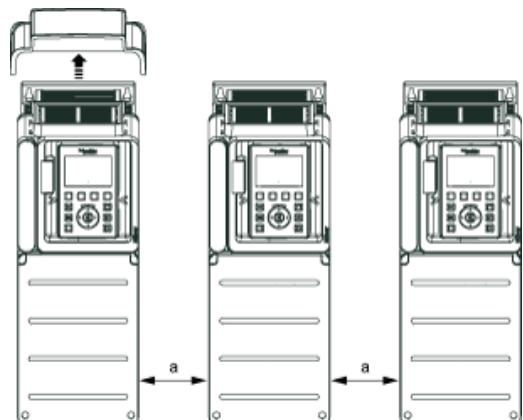


$a \geq = 110 \text{ mm (4.33 in.)}$

Mounting Type B: Side by Side IP20 (Possible, 2 Drives Only)



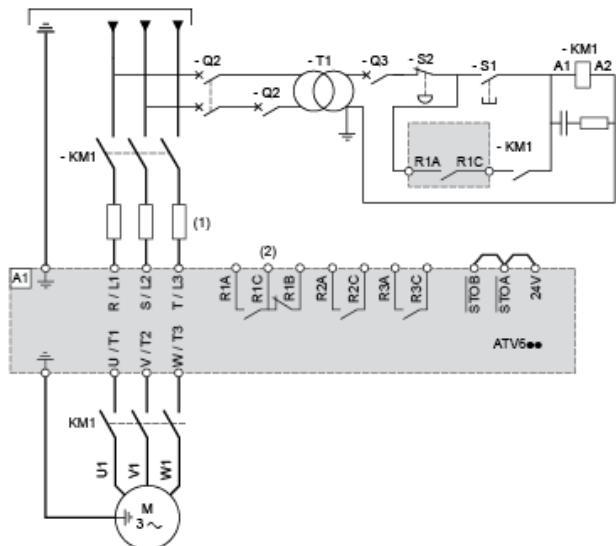
Mounting Type C: Individual IP20



$a \geq = 110$  mm (4.33 in.)

### Three-Phase Power Supply with Upstream Breaking via Line Contactor

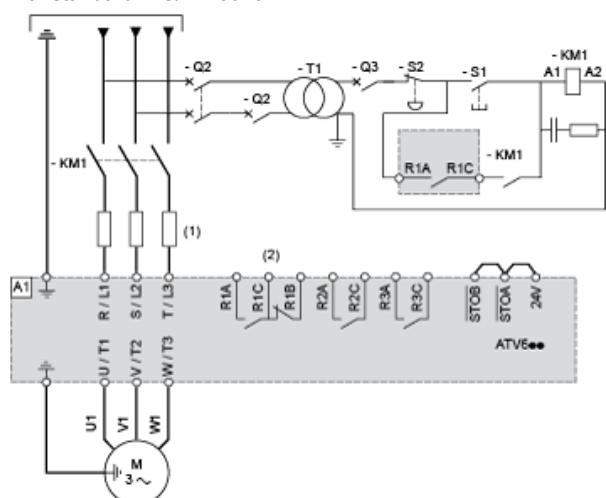
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
KM1 Line Contactor  
Q2, Circuit breakers  
Q3 :  
S1, Pushbuttons  
S2 :  
T1 : Transformer for control part

### Three-Phase Power Supply with Downstream Breaking via Contactor

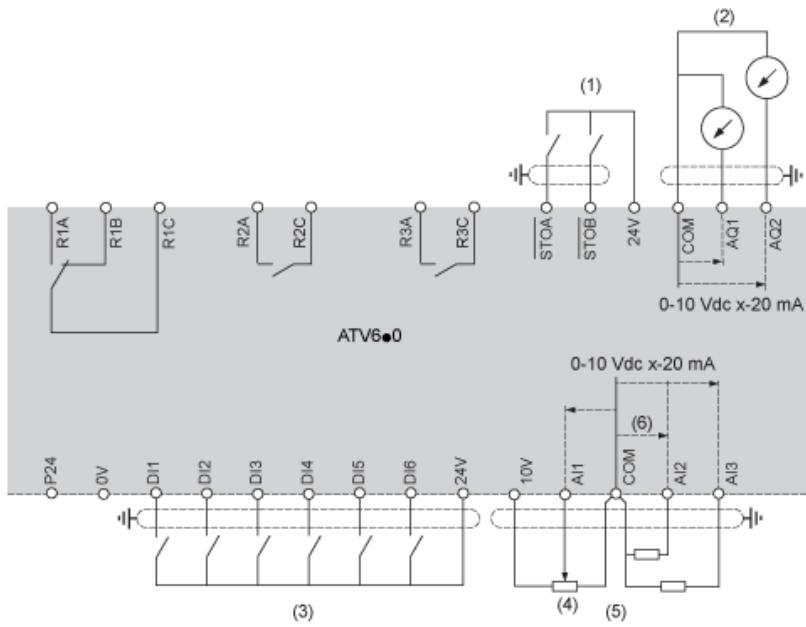
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
KM1 Contactor

## Control Block Wiring Diagram

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- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input

R1A, Fault relay

R1B,

R1C :

R2A, Sequence relay

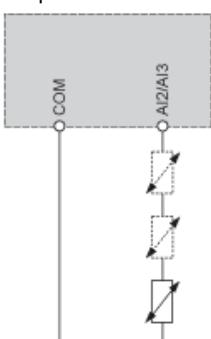
R2C :

R3A, Sequence relay

R3C :

### Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.



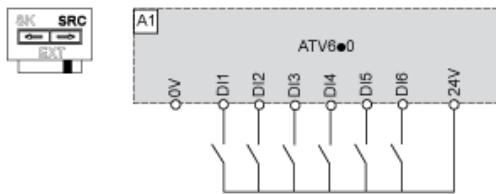
### Sink / Source Switch Configuration

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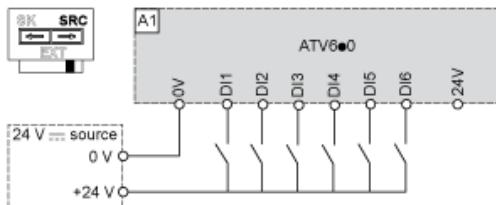
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

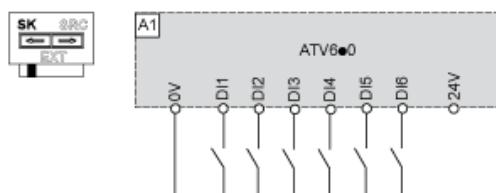
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



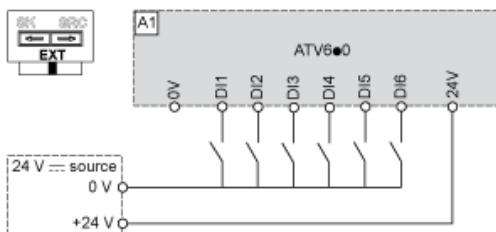
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the DIs



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Derating Curves

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